## Improved Deep Image Compositing Using Subpixel Masks

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### **OpenEXR 2.0 Deep Images**

Deep images are 2-D images with the capacity to store multiple color & depth samples (deep sample) at each pixel location (*deep pixel*)

Production facilities developed ad-hoc deep workflows over the years, often based on deep-shadow techniques

Weta Digital's deep workflow was formalized and integrated into OpenEXR 2.0

For more information on OpenEXR 2.0 deep images see: Hillman, P. 2013. The Theory of OpenEXR Deep Samples http://www.openexr.com/TheoryDeepPixels.pdf Kainz, F. 2013. Interpreting OpenEXR Deep Pixels http://www.openexr.com/InterpretingDeepPixels.pdf



Flat

### **OpenEXR 2.0 Workflow Challenges**

Works best when combining multiple volumetric renders

Not as well when combining volumetrics with one or more hard-surface renders

#### **Challenges With Hard-Surface Samples**

Lack of subpixel spatial information to resolve overlaps

Lack of spatial info prevents accurate pixel-filtering

Transparency and pixel-coverage are combined and cannot be separated

Intersections between opaque hard-surfaces will often exhibit aliasing





## Subpixel Masks

Generated by rendering algorithm

One mask per deep sample

Provides subpixel xy locations

Must ensure samples are stratified to avoid cracks



**Pattern/Bit Orientation** 



## Subpixel Masks

**Pros:** 

Resolves overlaps at subpixel level

Separates pixel-coverage from transparency

Accurate pixel-filtering is possible

Mask patterns will often compress well

#### **Cons:**

Fixed mask size for all samples

Separate pixel-coverage / transparency can complicate some compositing operations

Increased deep sample storage cost (can be offset by reduction in sample count)

Bit-pattern storage not natively supported by **OpenEXR 2.0** 

### Subpixel Mask – Special Cases



All bits off - zero coverage Indicates lack of subpixel information

> All bits on - full coverage Allows per-subpixel evaluation to be skipped (common for volumetric content)



## Subpixel Mask Overlap Resolution

Step through each subpixel index and flatten the samples with that bit enabled

Each subpixel index can yield a unique set of enabled samples

Integrating the flattened results of a region of subpixels produces the final anti-aliased pixel



## **Overlap Resolution Example**

Red and blue surfaces cover 50% of pixel

Both are opaque (alpha == 1.0)

### **A:**

Red surface completely occludes blue surface

#### **B:**

Red and blue surfaces do not occlude each other





### **Overlap Resolution: Current OpenEXR Method**

#### Both A and B produce the same incorrect result



#### Output Pixel Result

#### (0.5, 0.0, 0.25, 0.75)

#### Output Pixel Result



## **Overlap Resolution: Improved OpenEXR Method**

### A and B produce the correct result using subpixel masks



Α























## Sample Collapsing



Diverse sample set from the subpixel grid

Varying primitive/surface ID, color, normal, depth

Worst case scenario: a unique deep sample per subpixel

Must retain the integrity of the uncollapsed data

## Sample Collapsing: Static Micropolygon Example

### Naively inserting shaded micro-polygons





## Sample Collapsing: With Motion Blur

Motion blur and/or highly-tessellated geometry increases sample count A ray-tracer would exhibit similar problems.





## Sample Collapsing: Clustering

Determine which samples can be collapsed into clusters No single correct way to do this

Geometry ID Depth Color Normal

User controlled cluster limit

For each cluster:

Flatten the samples OR together the subpixel masks Determine the min/max Z

Each cluster becomes a single sample in the OpenEXR 2.0 file



## Sample Collapsing: Results



## Sample Collapsing: Results



## Surface Flags

Per-sample flags provide additional information about a deep sample

Backwards-compatible - value 0x00 (0.0) indicates a 'legacy' OpenEXR 2.0 deep sample

Proposed flags:

**0x01 (1.0)** Hard-Surface - use linear interpolation **0x02 (2.0)** Matte - act as a holdout to samples behind

Hard-Surface Flag: Why Bother With Linear Interpolation? By-product of collapsing samples (a Z range is created) Shared Z for all subpixels causes aliased intersections (binary Z comparison) Log interpolation intended for volumetric content Log interpolation fails when alpha = 1.0, a common case with hard-surfaces Hard-surface flag tells the flattener to use linear interpolation Linear interpolation allows Z-blending of hard-surface intersections to reduce aliasing

## Linear/Log Interpolation During Flattening

Find overlapping samples and determine mix of surface types:

Log/Log: OpenEXR log-interpolation

Log/Lin & Lin/Lin: Numerical vs. analytic



### Matte Flag – Holdout Management

- Matte holdouts are performed in the rendering algorithm
- An identifier indicates special-case handling of sample merge operation
- Alpha channel is held out along with color channels
- Current deep holdout workflow is destructive and can lead to loss of samples
- Non-destructive marking of samples allows holdout operation to be deferred



## Matte Flag Holdout Example

Nuke script producing mutual cutouts between two renders

#### Order-independent









#### bunny' = bunny - dragon

### OpenEXR 2.0 Deep File I/O

OpenEXR only supports 16 or 32 bit data channels

8x8 bitmask is 64 bits so must be split across two 32-bit **float** channels

32-bit float data channels avoid integer/float conversions destroying bitmask pattern

Flag data stored in 16-bit half-float channel as integer-float values will survive conversions

### Nuke Deep System Changes

We are working with the Foundry to get these modifications and new nodes released in a future version of Nuke

**DeepToImage** – modified flattening operator

**DeepSurfaceType** – modifies surface flag

**DeepMatte** – modifies matte flag

**DeepPremult** – premults/unpremults by pixel-coverage

**DeepCamDefocus** – camera defocus (bokeh) blur

**exrWriterDeep** – outputs subpixel mask channels as 32-bit float

### Future Work

Extend OpenEXR 2.0 & Nuke to support per-sample metadata

Encourage support from renderer providers

Store more surface information to better define hard-surface intersections (e.g. surface normal)



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